



US009346182B2

(12) **United States Patent**
Horii et al.

(10) **Patent No.:** **US 9,346,182 B2**
(45) **Date of Patent:** **May 24, 2016**

(54) **ROTARY DIE CUTTER**

USPC 83/346, 348, 658, 659, 506, 566, 343,
83/564; 72/238, 239; 225/46, 56; 156/552,
156/357, 516

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See application file for complete search history.

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(*) Notice: Subject to any disclaimer, the term of this patent is extended or adjusted under 35 U.S.C. 154(b) by 87 days.

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(21) Appl. No.: **14/480,663**

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(22) Filed: **Sep. 9, 2014**

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(65) **Prior Publication Data**

US 2015/0090089 A1 Apr. 2, 2015

(Continued)

(30) **Foreign Application Priority Data**

Oct. 1, 2013 (JP) 2013-206176

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(51) **Int. Cl.**

B23D 25/12 (2006.01)
B26D 5/08 (2006.01)
B26D 7/20 (2006.01)
B26F 3/02 (2006.01)
B65H 35/10 (2006.01)
B65C 9/22 (2006.01)
B29C 65/00 (2006.01)
B26D 7/26 (2006.01)

(Continued)

(57) **ABSTRACT**

Each pair of bearing units for each of magnet and anvil rollers are movable in a vertical direction. Each of large diameter portions of the anvil roller is supported by a pair of support rollers. Each of large diameter portions of the magnet roller is pressed against the corresponding large diameter portion of the anvil roller by a pair of press rollers. Each stopper is moved between a first position in which it projects into a clearance between vertically opposed bearing units and a second position in which it retracts from the first position. When the stoppers are located at the first position, the opposed large diameter portions of the magnet and anvil rollers separate from each other, and when the stoppers are located at the second position, the opposed large diameter portions of the magnet and anvil rollers contact with each other.

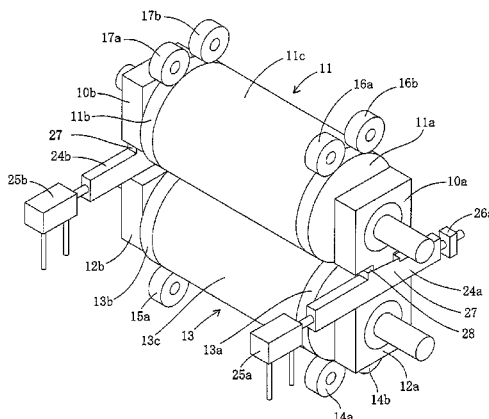
(52) **U.S. Cl.**

CPC **B26D 7/265** (2013.01); **B26F 1/384** (2013.01); **B26D 5/28** (2013.01); **B26D 7/0625** (2013.01); **Y10T 83/4833** (2015.04)

(58) **Field of Classification Search**

CPC B26D 7/265; B26D 7/0625; B26D 5/28; B26F 1/384; Y10T 83/4833

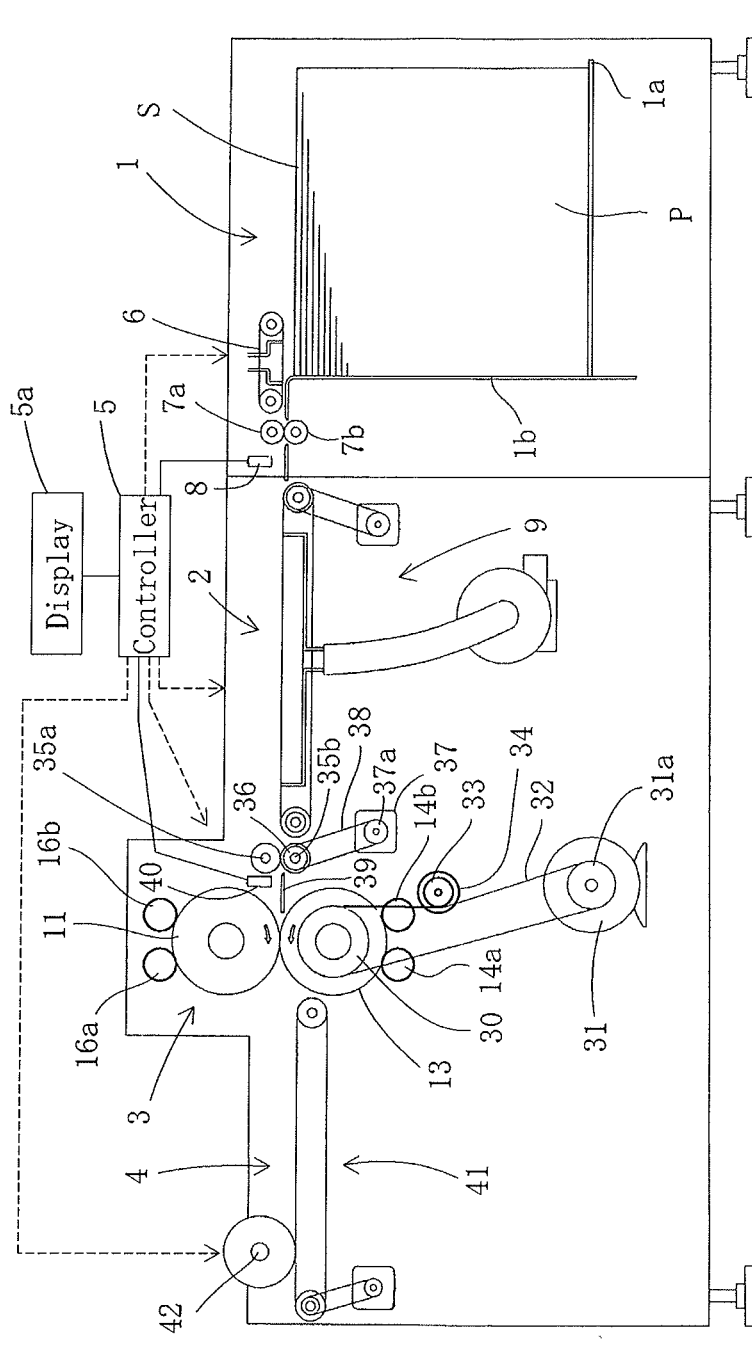
4 Claims, 6 Drawing Sheets



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FIG. 1



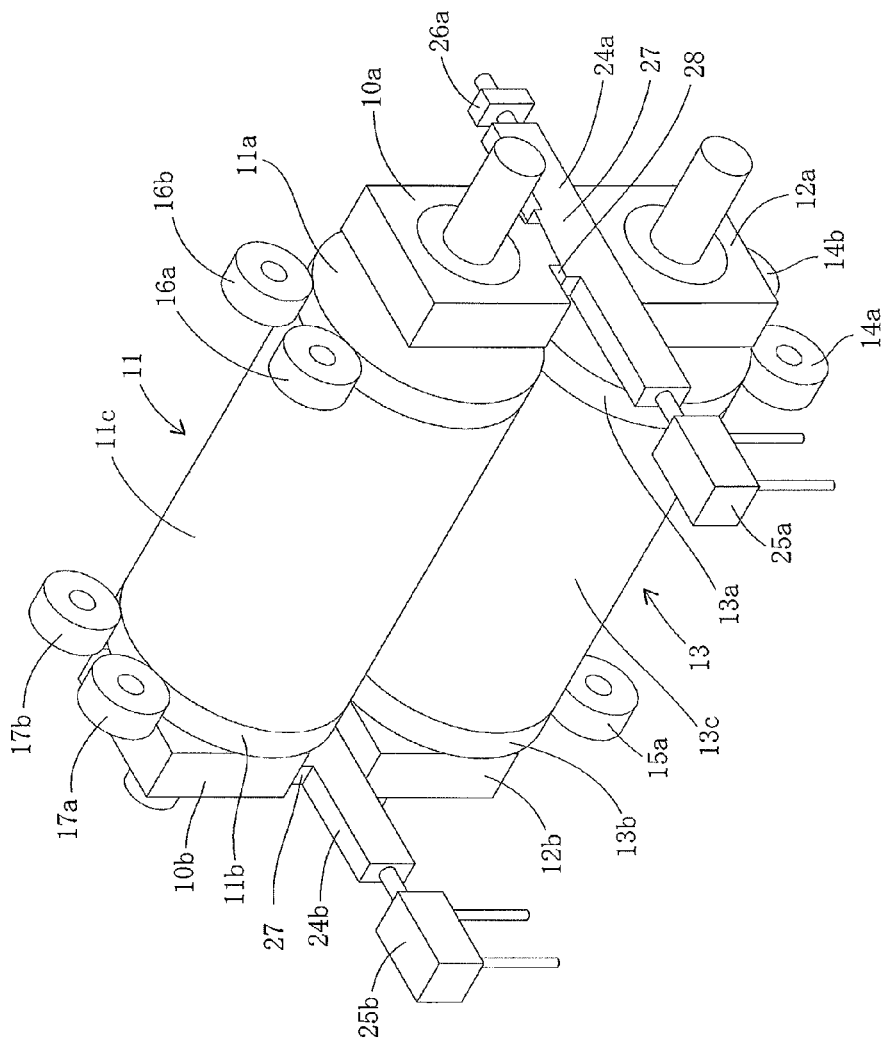


FIG. 2

FIG. 3A

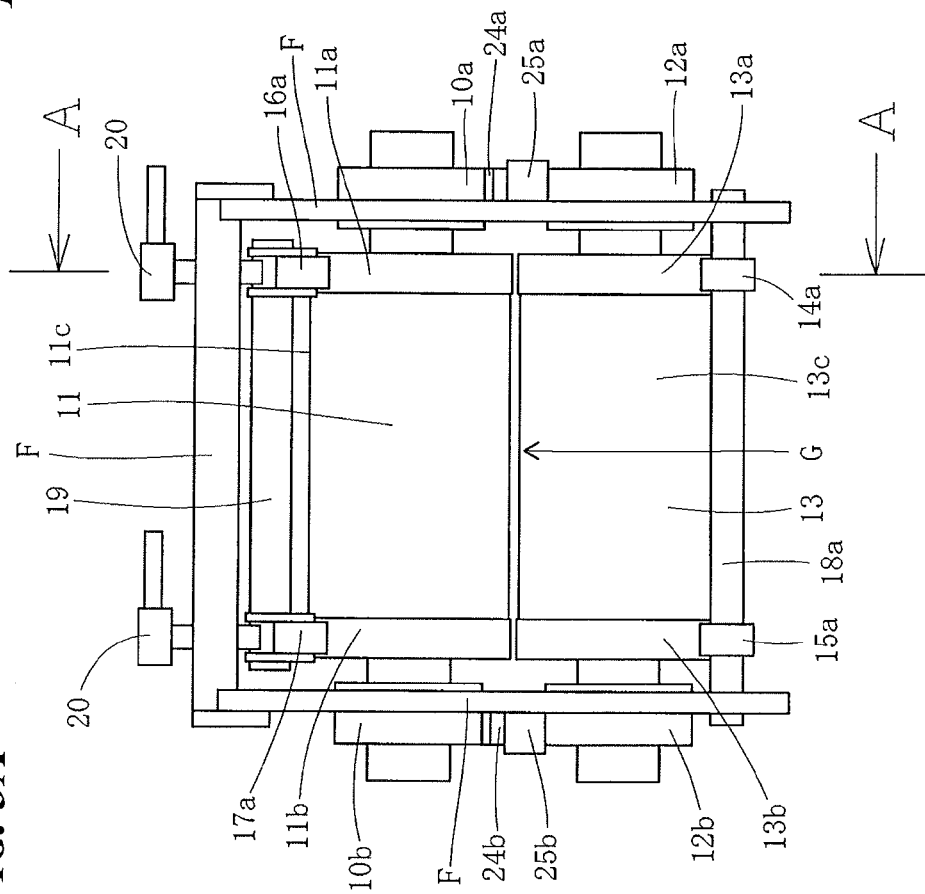


FIG. 3B

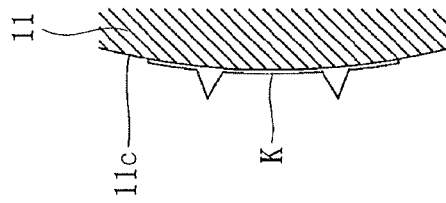


FIG. 3C

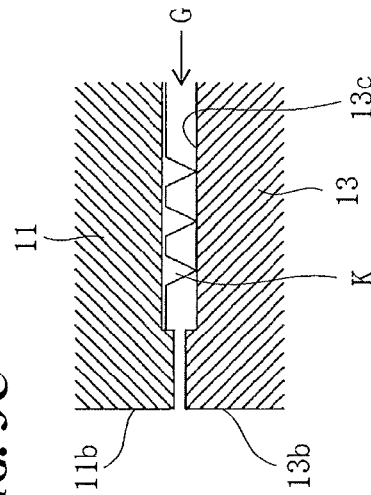


FIG. 4A

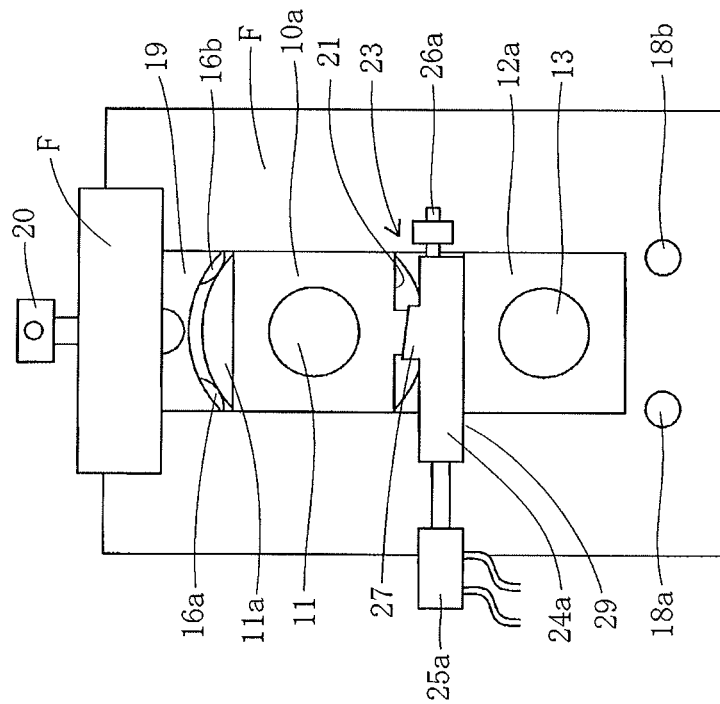


FIG. 4B

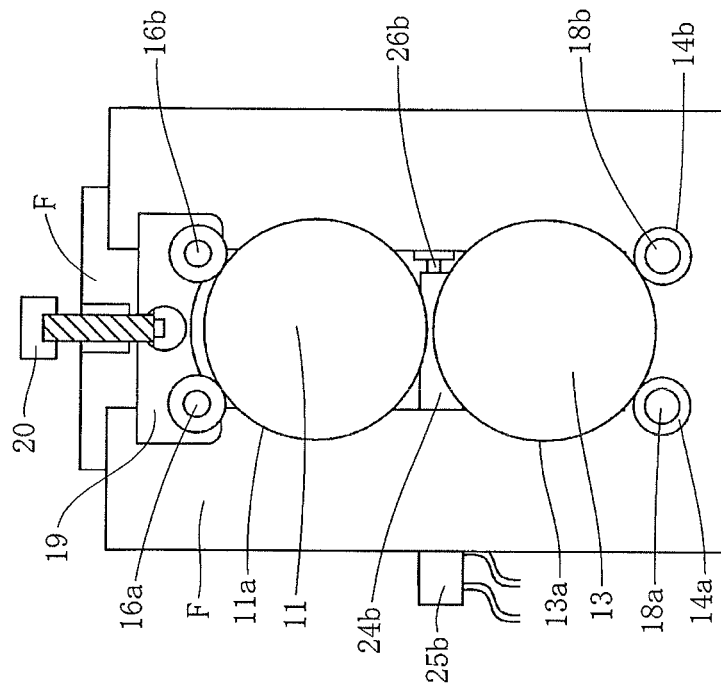


FIG. 5A

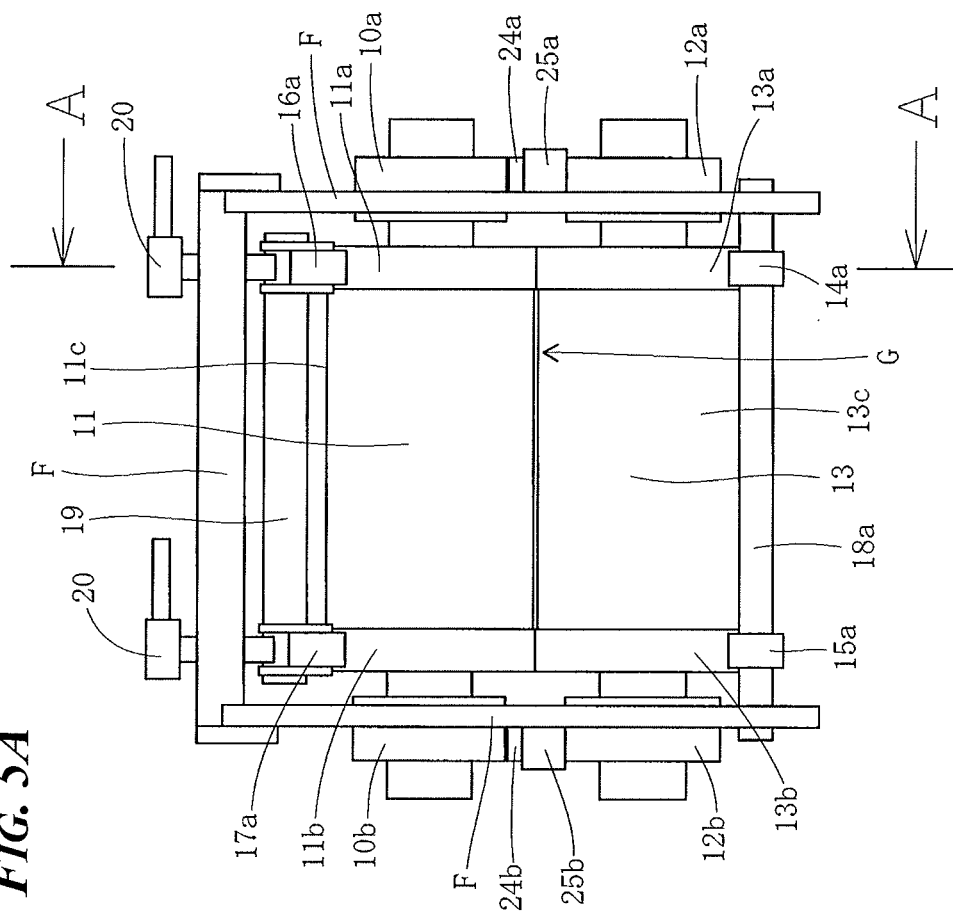


FIG. 5B

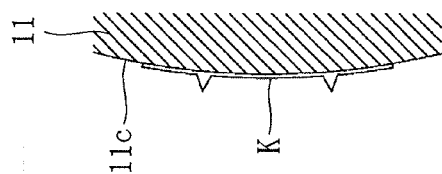
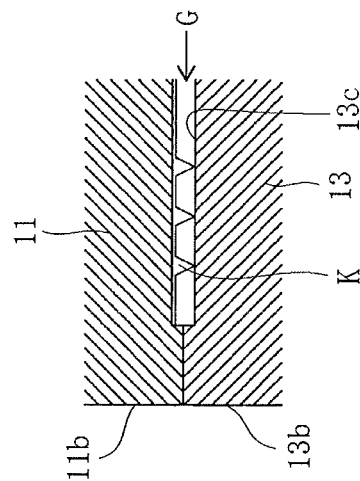
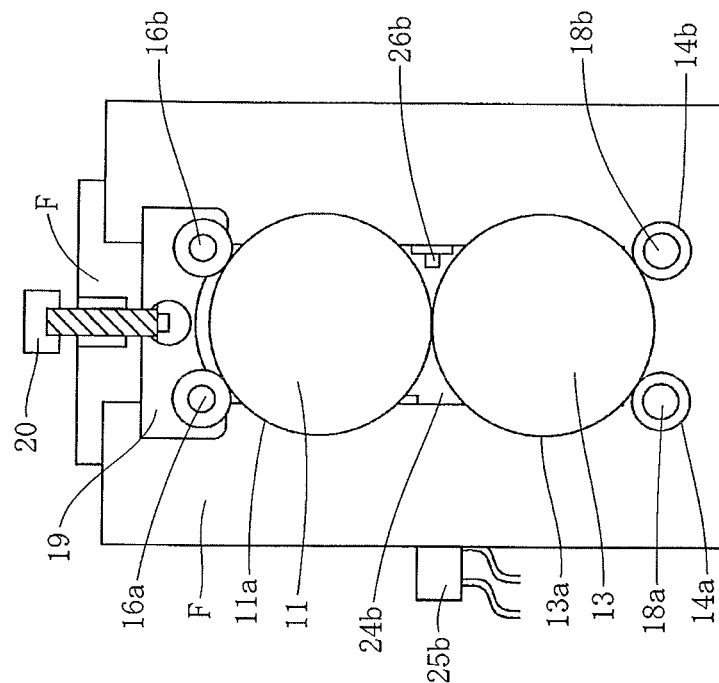
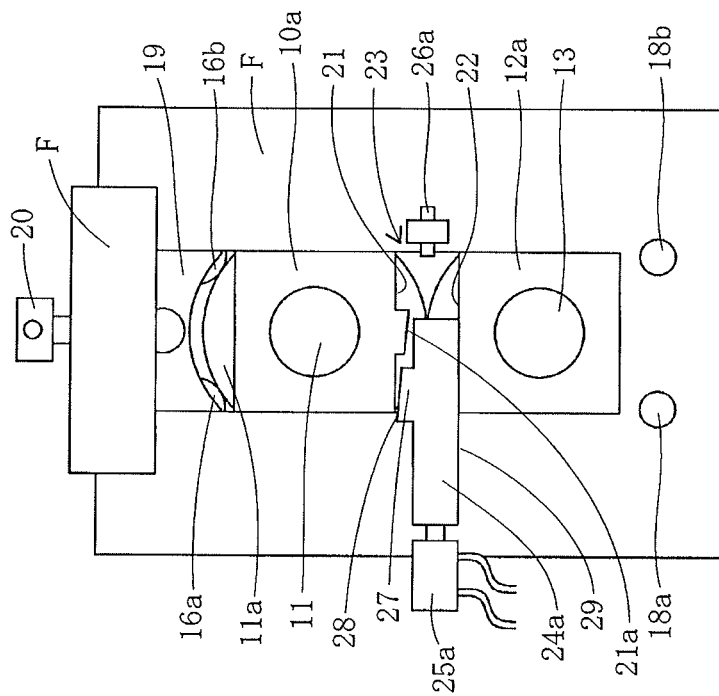


FIG. 5C





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ROTARY DIE CUTTER**TECHNICAL FIELD**

The present invention relates to a rotary die cutter having a pair of a magnet roller on which a flexible die is mounted, and an anvil roller arranged opposite to the magnet roller and punching out a sheet which is supplied one by one between the magnet roller and the anvil roller.

BACKGROUND ART

A conventional rotary die cutter comprises a magnet roller, an anvil roller arranged opposite to the magnet roller, a flexible die which is magnetically mounted on the magnet roller, and a sheet feed unit supplying a sheet one by one between the magnet and anvil rollers, in which the sheet supplied from the sheet feed unit is punched out by the flexible die (the term "punch" may be used to denote not only its original meanings but also "emboss", "score", "perforate" and so on. The same applies hereinafter.) while the sheet is conveyed by the magnet and anvil rollers (See, for example, JP 2003-237018 A and JP 2012-161859 A).

In such rotary die cutter, each of the magnet and anvil rollers forms large diameter portions (generally referred to as "bearers") at both ends thereof and a small diameter portion at intermediate portion thereof, and the small diameter portion extends between the large diameter portions. Then, when the magnet and anvil rollers contact with each other at their bearers, a gap corresponding to a height of the die is formed between the small diameter portions of the magnet and anvil rollers.

Then the die is magnetically mounted on the periphery of the small diameter portion of the magnet roller, and the bearer of the magnet roller and the bearer of the anvil rollers are pressed against each other in order to prevent a failure of punching by keeping the gap between the magnet and anvil rollers constant, and then the punching operation is performed.

However, according to such configuration, one type of the die whose height corresponds to the gap can only be used because the size of the gap between the magnet and anvil rollers cannot be changed. Therefore, a punching operation using various types of dies whose heights are different from each other is considerably inconvenient because a dedicated rotary die cutter is required for each type of the die.

SUMMARY OF THE INVENTION**Problems to be Solved by the Invention**

It is, therefore, an object of the present invention to provide a rotary die cutter capable of using two types of dies whose heights are different from each other.

Means for Solving the Problems

In order to achieve this object, according to the present invention, there is provided a rotary die cutter comprising: a frame provided with a path of sheets to be conveyed; a pair of first bearing units arranged at both sides of the path and attached to the frame so as to be moved in a vertical direction; a horizontal magnet roller supported by the pair of first bearing units and extending across and perpendicularly to the path; a pair of second bearing units arranged above or under the pair of first bearing units and attached to the frame so as to be moved in a vertical direction; a horizontal anvil roller

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supported by the pair of second bearing units and arranged opposite to the magnet roller, at least one of the magnet and anvil rollers forming large diameter portions at both ends thereof and a small diameter portion at intermediate portion thereof, the small diameter portion extending between the large diameter portions; a pair of support rollers attached to the frame and arranged under and opposite to each end of the lower roller of the magnet and anvil rollers so as to support the lower roller; a pair of press rollers arranged above and opposite to each end of the upper roller of the magnet and anvil rollers so as to be moved between a pressing position in which the pairs of press rollers press the both ends of the upper roller against both ends of the lower roller of the magnet and anvil rollers and a nonpressing position in which the pairs of press rollers retreat upward from the pressing position; a press mechanism attached to the frame so as to support and move the pairs of press rollers between the pressing position and the nonpressing position; a roller gap change unit attached to the frame and moving the bearing unit for the upper roller between a position in which the both ends of the magnet roller and the both ends of the anvil roller contact with each other and a position in which the both ends of the magnet roller and the both ends of the anvil roller separate from each other so as to switch between two different sizes of gaps between the intermediate portions of the magnet and anvil rollers, two different types of flexible dies whose heights correspond to the two different sizes of the gaps being able to magnetically mounted on the intermediate portion of the magnet roller; a pair of feed rollers arranged upstream of a pair of the magnet and anvil rollers; a first drive mechanism rotating the magnet and anvil rollers in such a way that the magnet and anvil rollers are rotated synchronously with each other at an equal circumferential velocity; and a second drive mechanism rotating the pair of feed rollers, wherein a sheet is supplied one by one between the pair of feed rollers, and punched by the flexible die while being conveyed through the gap between the magnet and anvil rollers by the pair of feed rollers.

According to a preferred embodiment of the present invention, a clearance is formed between each pair of the first bearing unit and the second bearing unit vertically opposed to each other when the both ends of the magnet roller and the both ends of the anvil roller contact with each other, wherein the roller gap change unit comprises: a slope formed on at least a part of one or both of the opposed surfaces of each pair of the first bearing unit and the second bearing unit; a stopper guided to move between a first position in which the stopper projects into the clearance and a second position in which the stopper retracts from the first position; and a stopper actuating mechanism attached to the frame so as to move the each of the stoppers, wherein each of the stoppers has an inclined surface engageable with the associated slope, and when each of the stoppers is located at the first position, the inclined surface of the stopper engages with the associated slope so that the both ends of the magnet roller and the both ends of the anvil roller separate from each other, and when each of the stoppers is located at the second position, the both ends of the magnet roller and the both ends of the anvil roller contact with each other, wherein the roller gap change unit further comprises a position adjusting mechanism provided for each of the stoppers and attached to the frame so as to be adjusted its position in a direction of linear movement of the associated stopper, and the leading end of the stopper contacts with the associated position adjusting mechanism when the stopper is located at the first position.

According to another preferred embodiment of the present invention, the stopper actuating mechanism is an air cylinder,

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and the stopper is fixed to a rod of the air cylinder. According to further preferred embodiment of the present invention, the stopper actuating mechanism is a solenoid actuator or a linear actuator including a motor as a drive source, and the stopper is fixed to an actuating element of the solenoid actuator or the linear actuator.

According to still further preferred embodiment of the present invention, the press mechanism comprises: a horizontal elongated roller support member extending above and parallel to the upper roller of the magnet and anvil rollers and movable in a vertical direction; and press screws vertically extending through the frame above both ends of the roller support member while engaging with the frame, wherein the press screws are attached to the roller support member so as to rotate around an axis thereof in their place, and the pairs of press rollers are supported by the both ends of the roller support member, and the pairs of press rollers are moved between the pressing position and the nonpressing position by the press screws being rotated in clockwise and counter-clockwise directions.

Effect of the Invention

According to the present invention, at least one of the magnet and anvil rollers forms large diameter portions at its both ends and a small diameter portions at its intermediate portion, and the pair of the bearing units for the magnet roller and the pair of the bearings for the anvil rollers are movable in a vertical direction, and each end of the lower roller of the magnet and anvil rollers is supported by the pair of support rollers, the both ends of the upper roller of the magnet and anvil rollers can be pressed against the both ends of the lower roller. Further, a roller gap change unit is arranged to move the bearing unit for the upper roller between a position in which the both ends of the magnet roller and the both ends of the anvil roller contact with each other and a position in which the both ends of the magnet roller and the both ends of the anvil rollers separate from each other, and thereby it is possible to switch between two different sizes of gaps between the intermediate portions of the magnet and anvil rollers. Consequently, two different types of flexible dies whose height correspond to the two different sizes of the gap can be magnetically mounted on the intermediate portion of the magnet roller and therefore, so that two different types of flexible dies having different heights can be used in a single rotary die cutter.

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a side view schematically showing a configuration of a rotary die cutter according to an embodiment of the present invention.

FIG. 2 is a perspective view illustrating a main part of a punching unit of the rotary die cutter shown in FIG. 1.

FIG. 3A is a perspective view of the punching unit shown in FIG. 2 as viewed from a downstream when each of stoppers is located at a first position.

FIGS. 3B and 3C are sectional views illustrating a situation of mounting of a flexible die when each of the stoppers is located at the first position.

FIG. 4A is a side view of the punching unit shown in FIG. 3A.

FIG. 4B is a sectional view taken along an A-A line in FIG. 3A.

FIG. 5A is a side view of the punching unit shown in FIG. 2 as viewed from the downstream when each of the stoppers is located at a second position.

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FIGS. 5B and 5C are sectional views illustrating a situation of mounting of a flexible die when each of stoppers is located at the second position.

FIG. 6A is side view of the punching unit shown in FIG. 5A.

FIG. 6B is a sectional view taken along an A-A line in FIG. 5A.

BEST MODE FOR CARRYING OUT THE INVENTION

A preferred embodiment of the present invention will be described below with reference to accompanying drawings. FIG. 1 is a side view schematically showing a configuration of a rotary die cutter according to an embodiment of the present invention. Referring to FIG. 1, a rotary die cutter according to the present invention comprises a sheet supply unit 1 supplying sheets S one by one from a sheet stack P, a conveyance unit 2 arranged downstream of the sheet supply unit 1 to convey the sheet S received from the sheet supply unit 1 while correcting the slant of the sheet S, a punching unit 3 arranged downstream of the conveyance unit 2, an ejecting unit 4 arranged downstream of the punching unit 3 to eject the punched sheet S, and a controller 5 controlling operations of the sheet supply unit 1, the conveyance unit 2, the punching unit 3 and the ejecting unit 4.

The sheet supply unit 1 comprises a horizontal shelf 1a, on which the sheet stack P is placed, arranged for a vertical movement, an elevating mechanism (not shown) moving the shelf 1a, and a suction conveyor unit 6 arranged above and opposite to the uppermost sheet S of the sheet stack P so as to suck the uppermost sheet S and discharge it forward beyond a sheet alignment plate 1b. In this embodiment, the suction conveyor unit 6 is composed of a suction conveyor belt, but, for example, a suction rotor may be used in place of the suction conveyor belt. Although not shown in the drawings, a sensor for detecting height of the sheet stack P on the shelf 1a is provided, and, based on detection signals of the sensor, the shelf 1a is raised by an amount corresponding to decrease in the height of the sheet stack P each time the height of the sheet stack P decreases by a certain amount.

Then the suction conveyor belt 6 is circulated and the suction operation of the suction conveyor belt 6 is repeated at certain intervals while the shelf 1a is raised by degrees in order to constantly put the uppermost sheet S of the sheet stack P within the range of suction by the suction conveyor belt 6, so that the sheets S are supplied one by one from the sheet supply unit 1.

A pair of feed rollers 7a, 7b is arranged adjacent to the downstream end of the suction conveyor belt 6. The pair of feed rollers 7a, 7b is constantly rotated in the direction in which the feed rollers 7a, 7b receive the sheet S from the suction conveyor belt 6, and the suction conveyor belt 6 is stopped whenever the sheet S is nipped between the pair of feed rollers 7a, 7b. A first sensor 8 is arranged at the exit of the pair of feed rollers 7a, 7b so as to detect the leading end of the sheet S. Detection signals of the first sensor 8 are sent to the controller 5.

In this embodiment, the conveyance unit 2 is composed of a suction conveyor belt 9. Although not shown in the drawings, a publicly known slant correction unit is arranged on the conveying surface of the suction conveyor belt 9 so as to correct the slant of the sheet S conveyed. Thus the suction conveyor belt 9 performs the suction while circulating so that the sheet S supplied from the sheet supply unit 1 is conveyed to the punching unit 3 while being sucked by the suction conveyor belt 9 at the underside thereof.

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FIG. 2 is a perspective view illustrating a main part of a punching unit of the rotary die cutter shown in FIG. 1. FIG. 3A is a perspective view of the punching unit shown in FIG. 2 as viewed from a downstream when each of stoppers is located at a first position, and FIGS. 3B and 3C are sectional views illustrating a situation of mounting of a flexible die when each of the stoppers is located at the first position. FIG. 4A is a side view of the punching unit shown in FIG. 3A, and FIG. 4B is a sectional view taken along an A-A line in FIG. 3A. FIG. 5A is a side view of the punching unit shown in FIG. 2 as viewed from the downstream when each of the stoppers is located at a second position. FIGS. 5B and 5C are sectional views illustrating a situation of mounting of a flexible die when each of the stoppers is located at the second position. FIG. 6A is side view of the punching unit shown in FIG. 5A, and FIG. 6B is a sectional view taken along an A-A line in FIG. 5A.

Referring to FIGS. 2 through 6, the punching unit 3 comprises a frame F provided with a path of the sheets S to be conveyed, a pair of first bearing units 10a, 10b arranged at both sides of the path and attached to the frame F so as to be moved in a vertical direction, a horizontal magnet roller 11 supported by the pair of first bearing units 10a, 10b and extending across and perpendicularly to the path, a pair of second bearing units 12a, 12b arranged under the pair of first bearing units 10a, 10b and attached to the frame F so as to be moved in a vertical direction, and a horizontal anvil roller 13 supported by the pair of second bearing units 12a, 12b and arranged opposite to the magnet roller 11.

In this case, positional relationship between the magnet and anvil rollers 11, 13 in a vertical direction is not limited to this embodiment, and the anvil roller 13 may be arranged above and opposite to the magnet roller 11.

Each of the magnet and anvil rollers 11, 13 forms large diameter portions 11a, 11b; 13a, 13b at its both ends and a small diameter portion 11c, 13c at its intermediate portion, the small diameter portion 11c, 13c extending between the large diameter portions 11a, 11b; 13a, 13b. In this embodiment, both of the magnet and anvil rollers 11, 13 have the large and small diameter portions 11a-11c; 13a-13c, but, instead, it is possible to adopt the configuration that one of the magnet and anvil rollers 11, 13 has the large and small diameter portions, and the other has a constant diameter along its length.

The punching unit 3 also comprises a pair of support rollers 14a, 14b; 15a, 15b attached to the frame F and arranged under and opposite to each of the large diameter portions 13a, 13b of the anvil roller 13 so as to support the anvil roller 13. In this embodiment, under the anvil roller 13, a pair of parallel rotary shafts 18a, 18b is supported by the frame F and extends parallel to the anvil roller 13. On each of the rotary shafts 18a, 18b, a pair of the support rollers 14a, 15a; 14b, 15b is mounted to be rotated with the associated rotary shaft 18a, 18b in an integrated fashion.

The punching unit 3 also comprises a pair of press rollers 16a, 16b; 17a, 17b arranged above and opposite to each of the large diameter portions 11a, 11b of the magnet roller 11 so as to be moved between a pressing position in which the pairs of press rollers 16a, 16b; 17a, 17b press the large diameter portions 11a, 11b of the magnet roller 11 against the large diameter portions 13a, 13b of the anvil roller 13 and a non-pressing position in which the pairs of press rollers 16a, 16b; 17a, 17b retract upward from the pressing position, and a press mechanism attached to the frame F so as to support and move the pairs of press rollers 16a, 16b; 17a, 17 between the pressing position and the nonpressing position.

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In this embodiment, the press mechanism comprises a horizontal elongated roller support member 19 extending above and parallel to the magnet roller 11 and movable in a vertical direction, and press screws 20 vertically extending through the frame F above both ends of the roller support member 19 while engaging with the frame F. The press screws 20 are attached to the roller support member 19 so as to rotate around an axis thereof in their place. The pairs of press rollers 16a, 16b; 17a, 17b are supported by the both ends of the roller support member 19. The pairs of press rollers 16a, 16b; 17a, 17b are moved between the pressing position and the non-pressing position by the press screws 20 being rotated in clockwise and counterclockwise directions.

In this embodiment, each of the first and second bearing units 10a, 10b, 12a, 12b is square plate-shaped, and has a bearing body at its center. When the large diameter portions 11a, 11b of the magnet roller 11 and the large diameter portions 13a, 13b of the anvil roller 13 contact with each other, a clearance 23 is formed between each pair of the first bearing unit 10a, 10b and the second bearing unit 12a, 12b which are vertically opposed to each other.

The upper surface 22 of each of the second bearing units 12a, 12b extends horizontally while the lower surface 21 of each of the first bearing units 10a, 10b projects downwardly (toward the associated second bearing unit 12a, 12b) at the middle thereof so as to form a slope 21a. In this embodiment, a part of the lower surface 21 of each of the first bearing units 10a, 10b forms the slope 21a, but, according to the present invention, at least one of the opposed surfaces 21, 22 of each pair of the first bearing unit 10a, 10b and the second bearing unit 12a, 12b which are vertically opposed to each other has only to be at least partially formed as a slope. Thus, for example, the whole of the lower surface 21 of each first bearing unit 10a, 10b may be formed as a slope, or both the lower surface 21 of each first bearing unit 10a, 10b and the upper surface 22 of each second bearing unit 12a, 12b may be at least partially formed as slopes. In the latter case, the slopes of the first and second bearing units 10a, 10b; 12a, 12b are opposed to each other so as to form wedge-shaped clearances therebetween.

In this embodiment, each of the first and second bearing units 10a, 10b; 12a, 12b is square plate-shaped, but the shape of the first and second bearing units 10a, 10b; 12a, 12b is not limited to this embodiment. Thus the first and second bearing units have arbitrary shapes in so far as the above-mentioned clearances and the above-mentioned slopes are formed.

The punching unit further comprises a roller gap change unit attached to the frame F and moving the first bearing units 10a, 10b between a position in which the both ends (in this embodiment, the large diameter portions 11a, 11b) of the magnet roller 11 and the both ends (in this embodiment, the large diameter portions 13a, 13b) of the anvil roller 13 contact with each other and a position in which the both ends of the magnet roller 11 and the both ends of the anvil roller 13 separate from each other so as to switch between two different sizes of gaps between the intermediate portions 11c, 13c of the magnet and anvil rollers 11, 13.

In this embodiment, the roller gap change unit has a stopper 24a, 24b provided for each pair of the opposed first and second bearing units 10a, 12a; 10b, 12b. Each of the stoppers 24a, 24b is guided to move between a first position in which the stopper 24a, 24b projects into the associated clearance 23 between the first and second bearing units 10a, 10b; 12a, 12b (see FIGS. 3 and 4) and a second position in which the stopper 24a, 24b retracts from the first position (see FIGS. 5 and 6). Each of the stoppers 24a, 24b is an elongated member having a square cross-section, and can slide in a horizontal direction

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along the upper surface 22 of the associated second bearing unit 12a, 12b at a flat side surface 29 thereof. Each of the stoppers 24a, 24b is also provided with a protruding portion 27 at the middle of the upper surface (a side surface opposite to the side surface 29) thereof, and the upper surface of the protruding portion 27 forms an inclined surface 28 engageable with the slope 21a of the associated first bearing unit 10a, 10b.

The roller gap change unit also has an air cylinder 25a, 25b provided for each stopper 24a, 24b and attached to the frame F. The stopper 24a, 24b is fixed to the associated air cylinder 25a, 25b. Thus the air cylinders 25a, 25b cause a reciprocating slide motion of the pair of stoppers 24a, 24b, and as shown in FIGS. 3 and 4, when the pair of stoppers 24a, 24b is located at the first position, the inclined surfaces 28 of the stoppers 24a, 24b engage with the slopes 21a of the first bearing units 10a, 10b so that the large diameter portions 11a, 11b of the magnet roller 11 and the large diameter portions 13a, 13b of the anvil rollers 13 separate from each other, on the other hand, as shown in FIGS. 5 and 6, when the pair of stoppers 24a, 24b is located at the second position, the engagement between the inclined surfaces 28 of the stoppers 24a, 24b and the slopes 21a of the first bearing units 10a, 10b is released so that the large diameter portions 11a, 11b of the magnet roller 11 and the large diameter portions 13a, 13b of the anvil roller 11 contact with each other. In this case, it goes without saying that such slide motion of the pair of stoppers 24a, 24b is carried out when the pair of press rollers 16a, 16b is located at the nonpressing position.

Although not shown in the drawings, position detection sensors (for example, proximity sensors) detecting when the stoppers 24a, 24b are located at the first or second positions are attached to the frame F, and detection signals of the position detection sensors are sent to the controller 5.

Thus the switching between two sizes of gaps G between the small diameter portion (intermediate portion) 11c of the magnet roller 11 and the small diameter portion (intermediate portion) 13c of the anvil roller 13 is achieved by switching between the first and second positions of the pair of stoppers 24a, 24b. As a result, two different types of flexible dies K whose heights correspond to the two different sizes of the gaps G can be magnetically mounted on the intermediate portion 11c of the magnet roller 11 (see FIGS. 3B, 3C, 5B and 5C).

The roller gap change unit further comprises a position adjusting mechanism 26a, 26b provided for each of the stoppers 24a, 24b. Each of the position adjusting mechanism 26a, 26b is arranged at a side of the frame F away from the air cylinder 25a, 25b and attached to the frame F so as to be adjusted its position in a direction of linear movement of the associated stopper 24a, 24b. The leading end of the stopper 24a, 24b contacts with the associated position adjusting mechanism 26a, 26b when the stopper 24a, 24b is located at the first position.

According to the present invention, the amount of the engagement between the slopes 21a of the first bearing units 10a, 10b and the inclined surfaces 28 of the stoppers 24a, 24b can be changed by the position adjusting mechanisms 26a, 26b and thereby the size of the gap G between the small diameter portion 11c of the magnet roller 11 and the small diameter portion 13c of the anvil roller 13 at the first position of the stoppers 24a, 24b can be easily changed or adjusted.

The configuration of the stoppers 24a, 24b is not limited to this embodiment. Thus the stoppers 24a, 24b may have any configuration adapted to shapes of the clearances between the pairs of the first bearing unit 10a, 10b and the second bearing unit 12a, 12b or shapes of the slopes of the lower and upper

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surfaces of the first and second bearing units 10a, 10b; 12a, 12b. In this embodiment, the air cylinder is used as a stopper actuating mechanism, but instead of the air cylinder, a solenoid actuator or a linear actuator including a motor as a drive source may be used, and each of the stoppers 24a, 24b is fixed to an actuating element of the solenoid actuator or the linear actuator.

In this embodiment, the roller gap change unit comprises the slope 21a formed at least one of the opposed surfaces 21, 22 of the first and second bearing units 10a, 12a; 10b, 12b which are vertically opposed to each other, the stopper actuating mechanisms composed of the air cylinders 25a, 25b, and the position adjusting mechanisms 26a, 26b, but the configuration of the roller gap change unit is not limited to this embodiment. Thus the roller gap change unit may be any configuration in so far as the roller gap change unit can switch between two sizes of the gaps G between the intermediate portions 11c, 13c of the magnet and anvil rollers 11, 13 by moving the first bearing units 10a, 10b in a vertical direction.

The switching of the size of the gap G is performed as follows. The controller 5 has a touch screen 5a, and for example, when preset sizes of the gap G are 0.8 mm and 1.0 mm, although not shown in the drawings, a button (an icon) marked "0.8 mm" and a button (an icon) marked "1.0 mm" are displayed on a screen for switch of gap size of the touch screen 5a. In this case, based on detection signals of the position detection sensors, the controller 5 indicates an operator which of the sizes is presently set by for example, highlighting one of the buttons.

Prior to the switching of the gap size, each pair of press rollers 16a, 16b; 17a, 17b is moved from the pressing position to the nonpressing position by the operator handling the press screws 20. Then, for example, when the present size of the gap G is 0.8 mm, the operator touches the button marked "1.0 mm" on the touch screen 5a, and the controller 5 responds to this touching to move the stoppers 24a, 24b (from the second position to the first position in this case). After that, each of the pairs of press rollers 16a, 16b; 17a, 17b is moved from the nonpressing position to the pressing position by the operator handling the press screws 20, and the switching of the gap size is completed.

Referring to FIG. 1 again, the anvil roller 13 is provided with a pulley 30 at a shaft thereof and a motor 31 is arranged below the anvil roller 13. A drive shaft of the motor 31 is provided with a pulley 31a and extends parallel to the anvil roller 13. A timing belt 32 extends between the pulleys 30, 31a. The anvil roller 13 is rotated by the motor 31. A shaft of the magnet roller 11 is coupled to the shaft of the anvil roller 13 through a connecting mechanism (not shown) in such a way that the magnet and anvil rollers 11, 13 are rotated synchronously with each other at an equal circumferential velocity.

The motor 31, the pulleys 30, 31a, the timing belt 32 and the connecting mechanism (not shown) construct a first drive mechanism rotating the magnet and anvil rollers 11, 13.

A rotary encoder 34 is arranged between the anvil roller 13 and the motor 31. A rotary shaft of the rotary encoder 34 is provided with a pulley 33 and extends parallel with the shaft of the anvil roller 13. The pulley 33 contacts with the timing belt 32 so as to be rotated by the circulation of the timing belt 32. The controller 5 detects a rotational position of the anvil roller 13, that is, the magnet roller 11 (that is, the flexible die K) based on pulses outputted from the rotary encoder 34.

The punching unit 3 further comprises a pair of feed rollers 35a, 35b arranged upstream of and at a distance from the pair of magnet and anvil rollers 11, 13 and arranged adjacent to the downstream of the suction conveyor belt 2. The pair of feed

rollers **35a**, **35b** consists of a pair of rollers which are arranged opposite to each other in a vertical direction and extend parallel to the magnet and anvil rollers **11**, **13**.

A lower roller **35b** of the pair of feed rollers **35a**, **35b** is provided with a pulley **36** at a shaft thereof. A servo motor **37** is arranged below the lower roller **35b**, and a drive shaft of the servo motor **37** is provided with a pulley **37a** and extends parallel to the lower roller **35b**. A timing belt **38** extends between the pulleys **36**, **37a** so that the pair of feed rollers **35a**, **35b** are rotated by the servo motor **37**. The servo motor **37**, the pulleys **36**, **37a** and the timing belt **38** construct a second drive mechanism rotating the pair of feed rollers **35a**, **35b**.

Thus the magnet and anvil rollers **11**, **13** are constantly rotated in a direction to receive the sheet S from the pair of feed rollers **35a**, **35b**, and the sheet S fed from the suction conveyor belt (conveyance unit) **2** into a gap between the pair of feed rollers **35a**, **35b** is punched by the flexible die K while being conveyed by the pair of feed rollers **35a**, **35b** through the gap between the magnet and anvil rollers **11**, **13**.

A second sensor **40** is arranged downstream of the pair of feed rollers **35a**, **35b** so as to detect the passage of a leading end of the sheet S. Detection signals of the second sensor **40** are sent to the controller **5**. A flat support plate **39** is arranged between the pair of feed rollers **35a**, **35b** and the pair of magnet and anvil rollers **11**, **13** so as to support the underside of the sheet S conveyed by the pair of feed rollers **35a**, **35b**. The support plate **39** is provided if needed.

Thus before start of the motion of the rotary die cutter, the data about the punching of the sheet such as a size of the sheet S and a distance from the leading end of the sheet S to a leading end of a punching range on the sheet S is inputted to the controller **5** through the touch screen **5a**. Then the rotary die cutter starts the motion, and when a first sheet S is supplied from the sheet stack P by the sheet supply unit **1**, the controller **5** measures a time from when the suction conveyor belt **6** of the sheet supply unit **1** starts the motion till when the leading end of the first sheet S passes through the second sensor **40**. Thus a timing of sheet supply by the sheet supply unit **1**, that is, a timing of the motion of the suction conveyor belt **6** is corrected based on difference between the measured value and the preset value.

After that, subsequent sheets S after a second sheet S are supplied by the sheet supply unit **1** one by one at the corrected timing. The sheet S supplied from the sheet supply unit **1** is conveyed by the suction conveyor belt **2**, and fed from the suction conveyor belt **2** into the gap between the pair of feed rollers **35a**, **35b**. In this case, the suction conveyor belt **2** is constantly circulated.

In addition to the correction of the timing of sheet supply of the sheet supply unit **1**, the rotation of the pair of feed rollers **35a**, **35b** is controlled based on the detection signals of the second sensor **40**. Thus the sheet S fed to the pair of feed rollers **35a**, **35b** is conveyed to the gap between the magnet and anvil rollers **11**, **13** along the support plate **39** by the pair of feed rollers **35a**, **35b**. When the leading end of the sheet S passes through the second sensor **40**, based on the detection signal of the sensor **40**, the rotation of the pair of feed rollers **35a**, **35b** is controlled corresponding to a peripheral velocity and a rotational position of the flexible die K in such a manner that the leading end of the punching range on the sheet S coincides with the leading end of the flexible die K at the lowest point of the periphery of the magnet roller **11**.

The sheet supply to the pair of magnet and anvil rollers **11**, **13** at a precise timing by the control of the rotation of the pair of feed rollers **35a**, **35b** based on the detection signals of the second sensor **40** as well as the correction of the timing of sheet supply of the sheet supply unit **1**.

The ejecting unit **4** comprises a conveyor belt **41** extending from an exit of the pair of magnet and anvil rollers **11**, **13** to an exit of the rotary die cutter, a feed roller **42** arranged adjacent to the downstream of the conveyor belt **41**. The feed roller **42** extends perpendicularly to the conveyor belt **41** and contacts the conveyance surface of the conveyor belt **41**. The sheet S punched by the punching unit **3** is conveyed by the conveyor belt **41** and the feed roller **42** and discharged from the exit of the rotary die cutter.

DESCRIPTION OF REFERENCE NUMERALS

- 1** Sheet supply unit
- 1a** Shelf
- 1b** Sheet alignment plate
- 2** Conveyance unit (Suction conveyor belt)
- 3** Punching unit
- 4** Ejecting unit
- 5** Controller
- 5a** Touch screen
- 6** Suction conveyor belt
- 7a**, **7b** Pair of feed rollers
- 8** First sensor
- 9** Suction conveyor belt
- 10a**, **10b** First bearing unit
- 11** Magnet roller
- 11a**, **11b** Large diameter portion
- 11c** Small diameter portion
- 12a**, **12b** Second bearing unit
- 13** Anvil roller
- 13a**, **13b** Large diameter portion
- 13c** Small diameter portion
- 14a**, **14b**, **15a**, **15b** Support roller
- 16a**, **16b**, **17a**, **17b** Press roller
- 18a**, **18b** Rotary shaft
- 19** Roller support member
- 20** Press screw
- 21** Lower surface
- 21a** Slope
- 22** Upper surface
- 23** Clearance
- 24a**, **24b** Stopper
- 25a**, **25b** Air cylinder
- 26a**, **26b** Position adjusting mechanism
- 27** Protruding portion
- 28** Inclined surface
- 29** Side surface
- 30** Pulley
- 31** Motor
- 31a** Pulley
- 32** Timing belt
- 33** Pulley
- 34** Rotary encoder
- 35a**, **35b** Pair of feed rollers
- 36** Pulley
- 37** Servo motor
- 38** Timing belt
- 39** Support plate
- 40** Second sensor
- 41** Conveyor belt
- 42** Feed roller
- F Frame
- G Gap
- K Flexible die
- P Sheet stack
- S Sheet

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The invention claimed is:

1. A rotary die cutter comprising:

a frame provided with a path of sheets to be conveyed;
a pair of first bearing units arranged at both sides of the path
and attached to the frame;

one roller of a magnet roller and an anvil roller supported
by the pair of first bearing units and extending across and
perpendicularly to the path;

a pair of second bearing units arranged above the pair of
first bearing units and attached to the frame so as to be
moved in a vertical direction;

the other roller of the magnet roller and the anvil roller
supported by the pair of second bearing units and
arranged opposite to the one roller, at least one of the
magnet and anvil rollers forming large diameter portions
at both ends thereof and a small diameter portion at an
intermediate portion thereof, the small diameter portion
extending between the large diameter portions;

a pair of support rollers attached to the frame and arranged
under and opposite to each end of the one roller so as to
support the one roller;

a pair of press rollers arranged above and opposite to each
end of the other roller so as to be moved between a
pressing position in which the pairs of press rollers press
the both ends of the other roller against the both ends of
the one roller and a nonpressing position in which the
pairs of press rollers retreat upward from the pressing
position;

a press mechanism attached to the frame so as to support
and move the pairs of press rollers between the pressing
position and the nonpressing position;

a roller gap change unit attached to the frame and moving
the bearing unit for the other roller between a position in
which the both ends of the magnet roller and the both
ends of the anvil roller contact with each other and a
position in which the both ends of the magnet roller and
the both ends of the anvil roller separate from each other
so as to switch between two different sizes of gaps
between the intermediate portions of the magnet and
anvil rollers, two different types of flexible dies whose
heights correspond to the two different sizes of the gaps
being able to be magnetically mounted on the interme-
diate portion of the magnet roller;

a pair of feed rollers arranged upstream of a pair of the
magnet and anvil rollers;

a first drive mechanism rotating the magnet and anvil roll-
ers in such a way that the magnet and anvil rollers are
rotated synchronously with each other at an equal cir-
cumferential velocity; and

a second drive mechanism rotating the pair of feed rollers,
wherein a clearance is formed between each pair of the first
bearing unit and the second bearing unit vertically
opposed to each other when the both ends of the ma net
roller and the both ends of the anvil roller contact with
each other,

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wherein the roller map change unit comprises:

a slope formed on at least a part of one or both of the
opposed surfaces of each pair of the first bearing unit
and the second bearing unit;

a stopper guided to move between a first position in
which the stopper projects into the clearance and a
second position in which the stopper retracts from the
first position; and

a stopper actuating mechanism attached to the frame so
as to move the each of the stoppers,

wherein each of the stoppers has an inclined surface
engageable with the associated slope, and when each
of the stoppers is located at the first position, the
inclined surface of the stopper engages with the asso-
ciated slope so that the both ends of the magnet roller
and the both ends of the anvil roller separate from
each other, and when each of the stoppers is located at
the second position, the both ends of the magnet roller
and the both ends of the anvil roller contact with each
other,

wherein the roller gap change unit further comprises a
position adjusting mechanism provided for each of the
stoppers and attached to the frame so as to be adjusted at
a position thereof in a direction of linear movement of
the associated stopper, and the leading end of stopper
contacts with the associated position adjusting mecha-
nism when the stopper is located at the first position,

wherein a sheet is supplied one by one between the pair of
feed rollers, and punched by the flexible die while being
conveyed through the gap between the magnet and anvil
rollers by the pair of feed rollers.

2. The rotary die cutter according to claim 1, wherein the
stopper actuating mechanism is an air cylinder, and wherein
the stopper is fixed to a rod of the air cylinder.

3. The rotary die cutter according to claim 1, wherein the
stopper actuating mechanism is a solenoid actuator or a linear
actuator including a motor as a drive source, and wherein the
stopper is fixed to an actuating element of the solenoid actua-
tor or the linear actuator.

4. The rotary die cutter according to claim 1, wherein the
press mechanism comprises:

a horizontal elongated roller support member extending
above and parallel to the other roller and movable in a
vertical direction; and

press screws vertically extending through the frame above
both ends of the roller support member while engaging
with the frame, wherein

the press screws are attached to the roller support member
so as to rotate around an axis thereof in their place, and
the pairs of press rollers are supported by the both ends
of the roller support member, and the pairs of press
rollers are moved between the pressing position and the
nonpressing position by the press screws being rotated in
clockwise and counterclockwise directions.

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